

ST for urban mapping and citizen science

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With contribution of T2.3 partners and DCMR

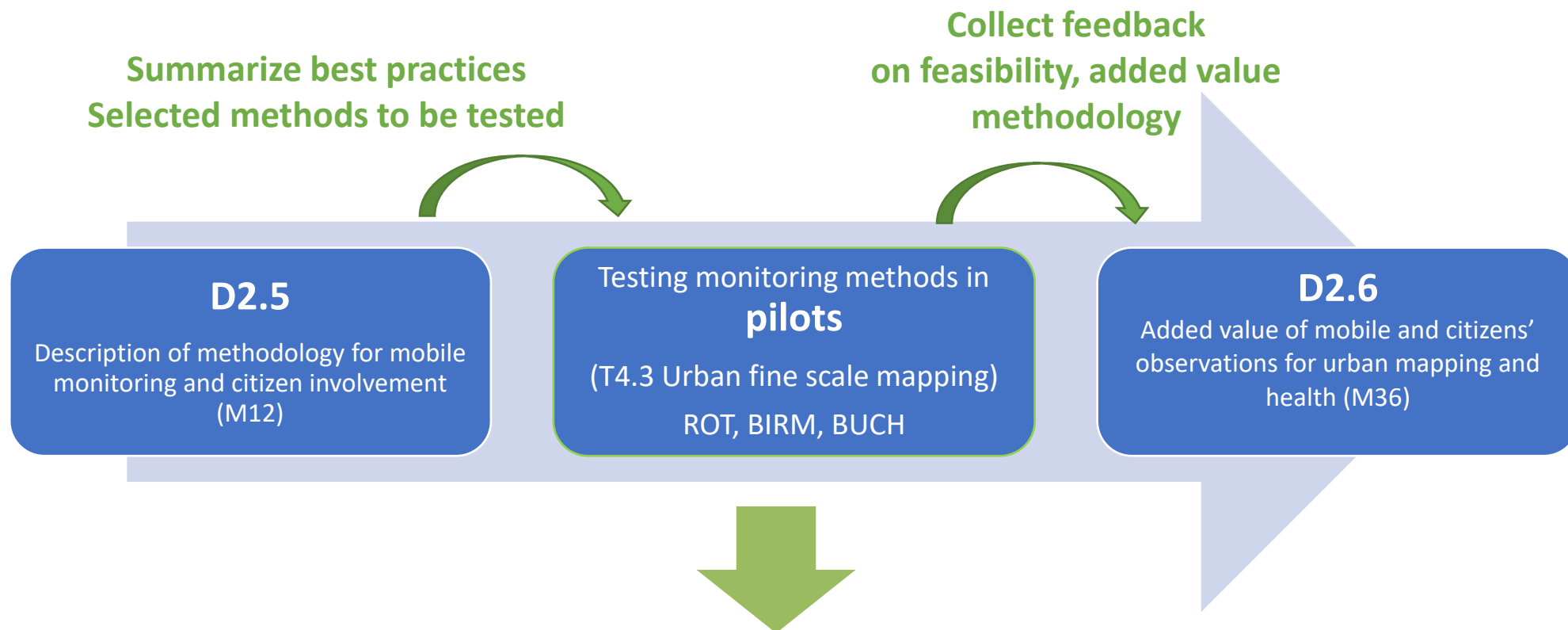
ST13 Urban mapping and Citizen Science

WHAT?

- a methodology for mapping of UFP and other pollutants
- using mobile platforms and sensor networks (with involvement of citizens)
- for the generation of high spatial resolution exposure maps

T2.3 Urban AQ mapping

Mobile monitoring of nanoparticles and citizen observatories to improve evaluation of health effects



ST13: URBAN AQ MAPPING AND CITIZEN SCIENCE

PILOTS

Birmingham (UK)



Fixed and mobile setups with citizens (UFP, BC, PM_{2.5})

Involvement of local community (stationary), students (mobile)

ML used to predict PM_{2.5} concentration

Case studies: neighborhood & street level AQ, prediction PM_{2.5}, indoor AQ



Rotterdam (NL)

Mobile monitoring without citizens (UFP, BC, PM_{2.5}, NO₂)

Dedicated; two seasons, car with high-end equipment, repeated measurements aggregated over each 50 m street segment per day (~40000 segments)



Rotterdam (NL)

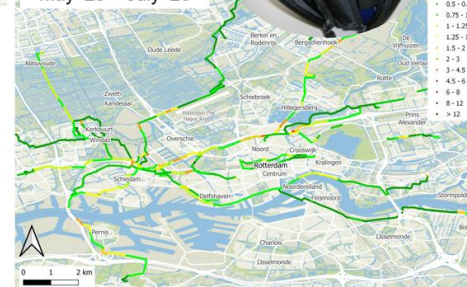
Mobile monitoring with citizens (BC)

Opportunistic; two seasons, 38 participants, repeated measurements n=4-21 individual route, up to n=65 at street segment level
Background normalization/winsorizing/Subsampling:
>15 repeats within season/>30 repeats cross-season

WINTER_norm Nov '22 – Mar '23

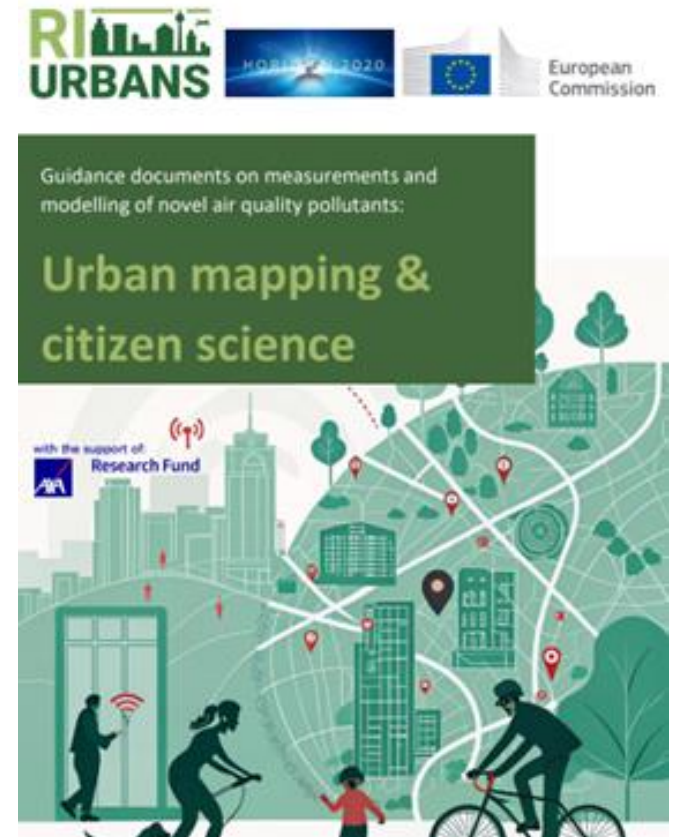


SUMMER_norm May '23 – July '23



ST 13: Main findings

- Substantial new information can be learned by campaigns of mobile monitoring or low-cost sensor (LCS) fixed site monitoring
 - limited duration (weeks to months)
 - with a proper design
- These methods are useful as an addition to routine monitoring with reference grade instruments at a small number of fixed sites
 - Longer campaigns can result in more precise estimates of air pollution patterns
- Participatory approach is valuable tool to generate a lot of data



CONCLUSIONS and best practices

- Different approaches have been applied in pilot cities
 - Insights compiled in ST13
- Best practices:
 - With citizens
 - Valuable knowledge → domain experts
 - Single POC/communication is key/templates/on-site training
 - Provides a lot data!
 - Validation instruments
 - Co-location campaign
 - between instruments (BSU) + comparison against REF
 - ideally on-site/similar conditions
 - Data collection:
 - Dedicated vs opportunistic
 - Number of required repeats (>15 within season vs >30 multi-season)
 - Data analysis
 - Time/GPS synchronization
 - Data cleaning
 - Post-processing (Map matching/background normalization/winsorizing/...)
 - Number of required repeats (measurements only) vs model approach



Guidance documents on measurements and modelling of novel air quality pollutants:

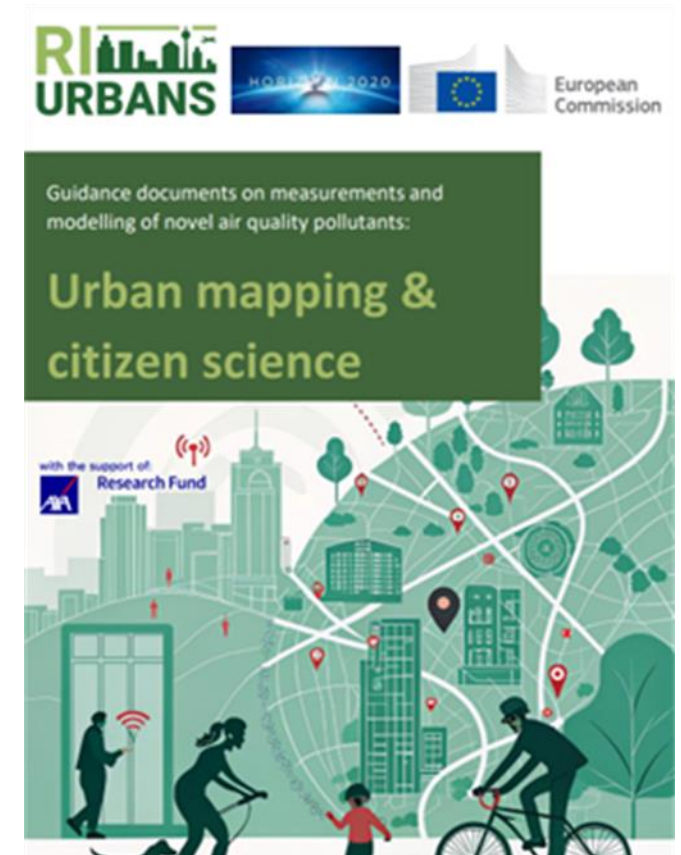
Urban mapping & citizen science



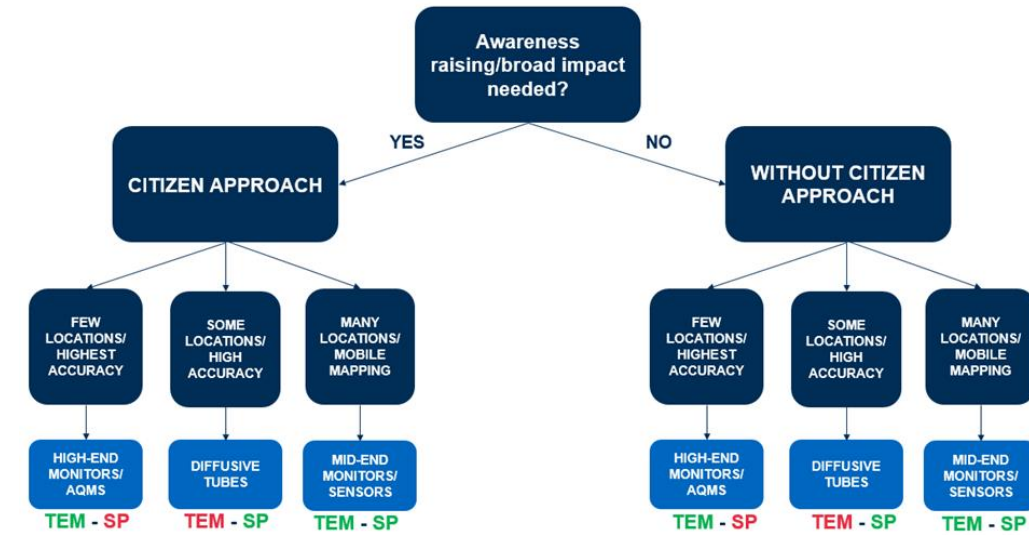
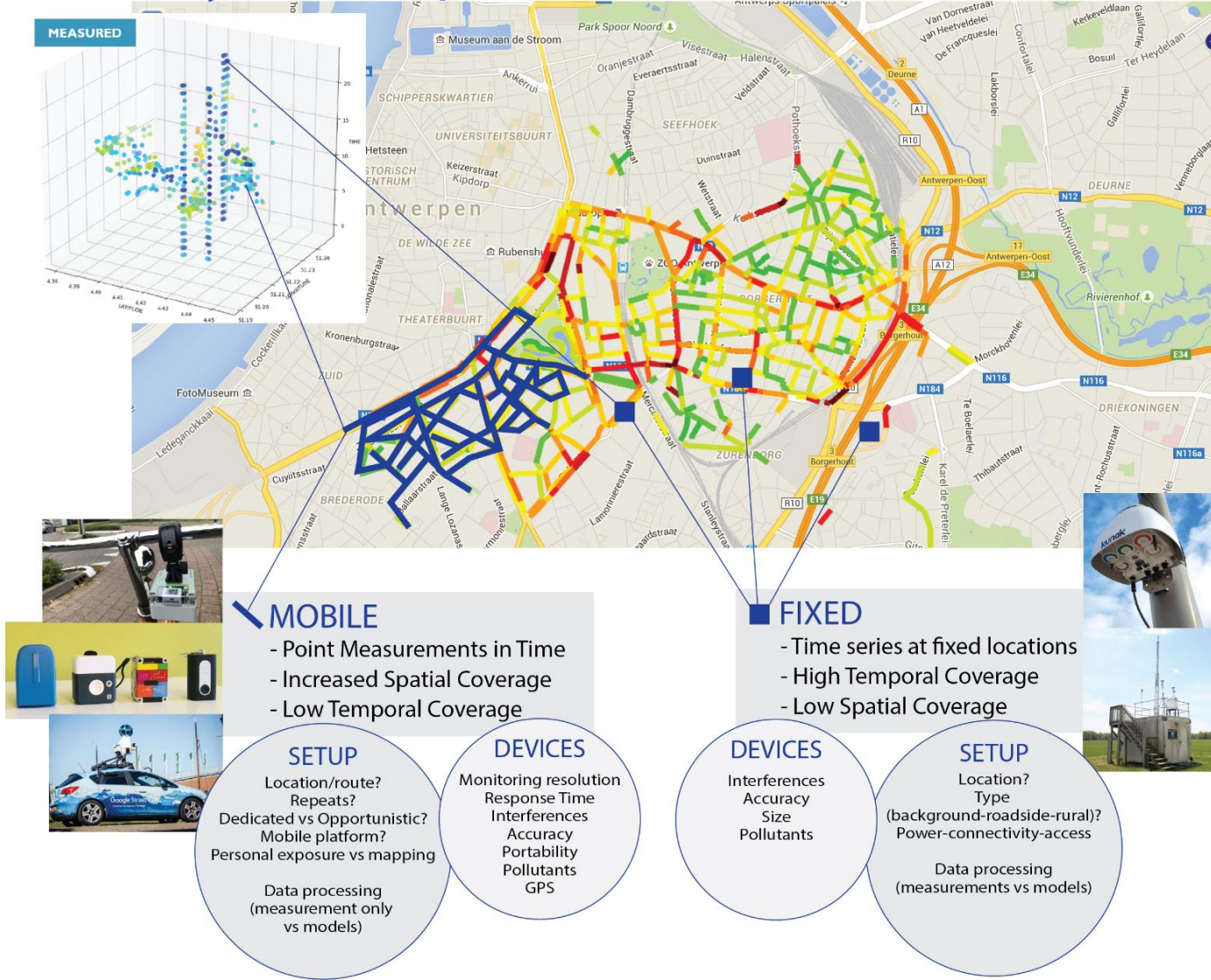
ST13: Recommendations

- Monitoring strategy and instrumentation
- Involvement of citizens
- Data processing
- Modelling strategy
- Results

→ For more details see:

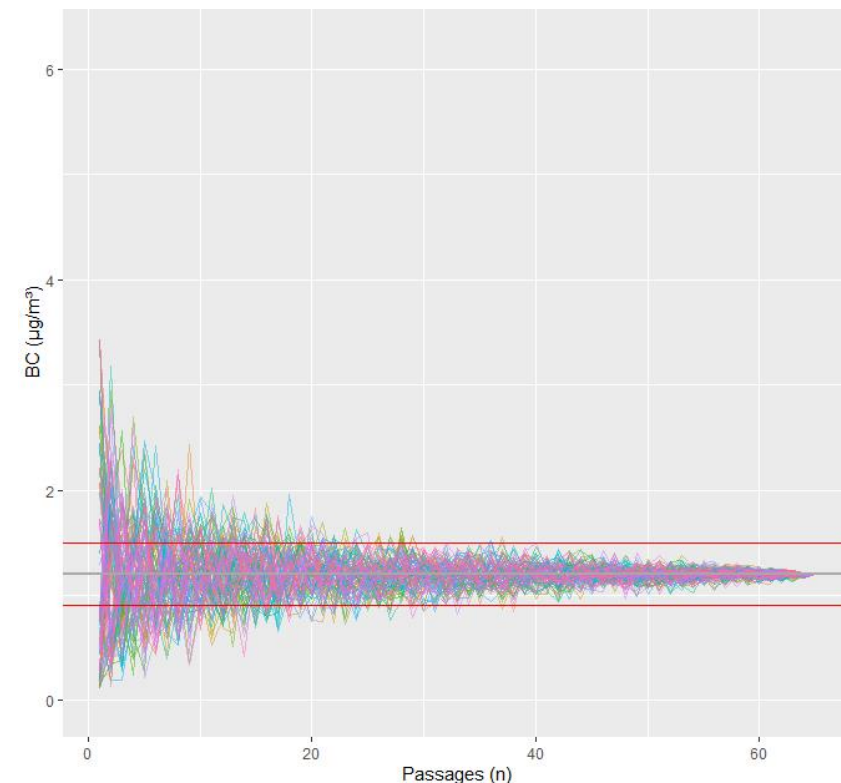


Monitoring strategy and instrumentation (1/2)



Monitoring strategy and instrumentation (2/2)

- Mobile approach:
 - **Dedicated** vs **opportunistic**
 - **Vehicle** vs **portable**
 - **Different seasons** to capture seasonal variability (sources, dispersion, meteo,...)
 - Minimum **number of repeats!**
 - Period of interest: peak hours, working days, annual average...
- Stationary approach: low-cost sensors
 - Quality control!
- Stationary approach: diffusive tubes
 - Low time resolution

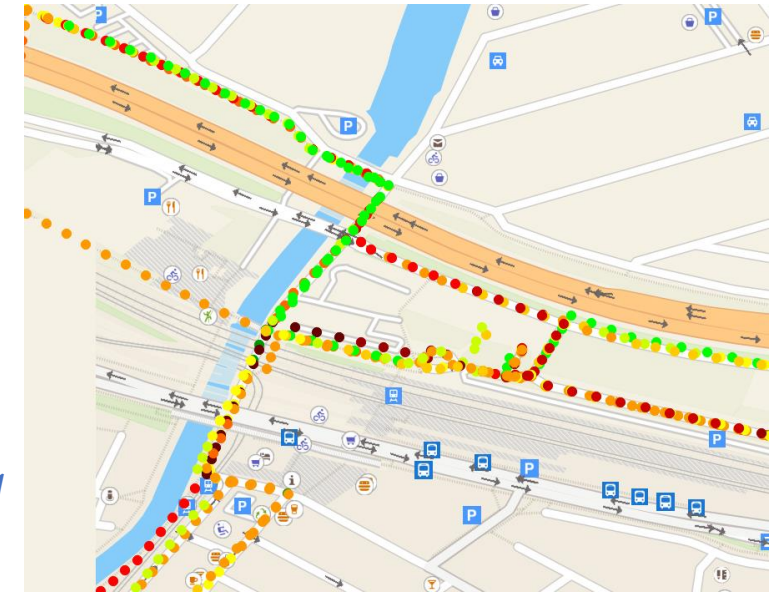
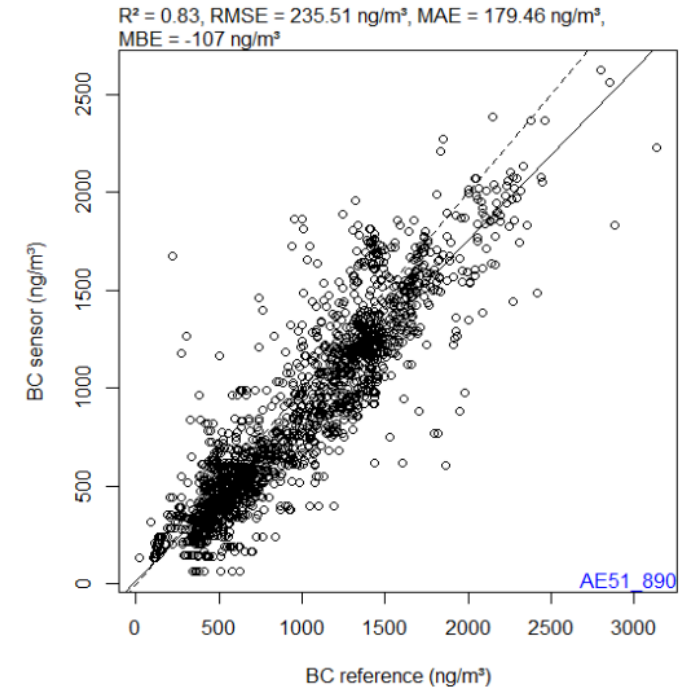


Involvement of citizens

- Instructions!
 - Operation of instruments
 - when and where to collect data
 - Central point of contact
 - Aim of the research
- Engagement and interactions with citizens
 - Building trust, anonymity (ethics)
 - Feedback of results (e.g. luchtalk at DCMR for participants)
 - Reward, interest in own environment
- Recruitment process
- Added value of including citizens:
 - Valuable knowledge → domain experts
 - Awareness raising, identification hotspots, representative exposure assessments

Data processing

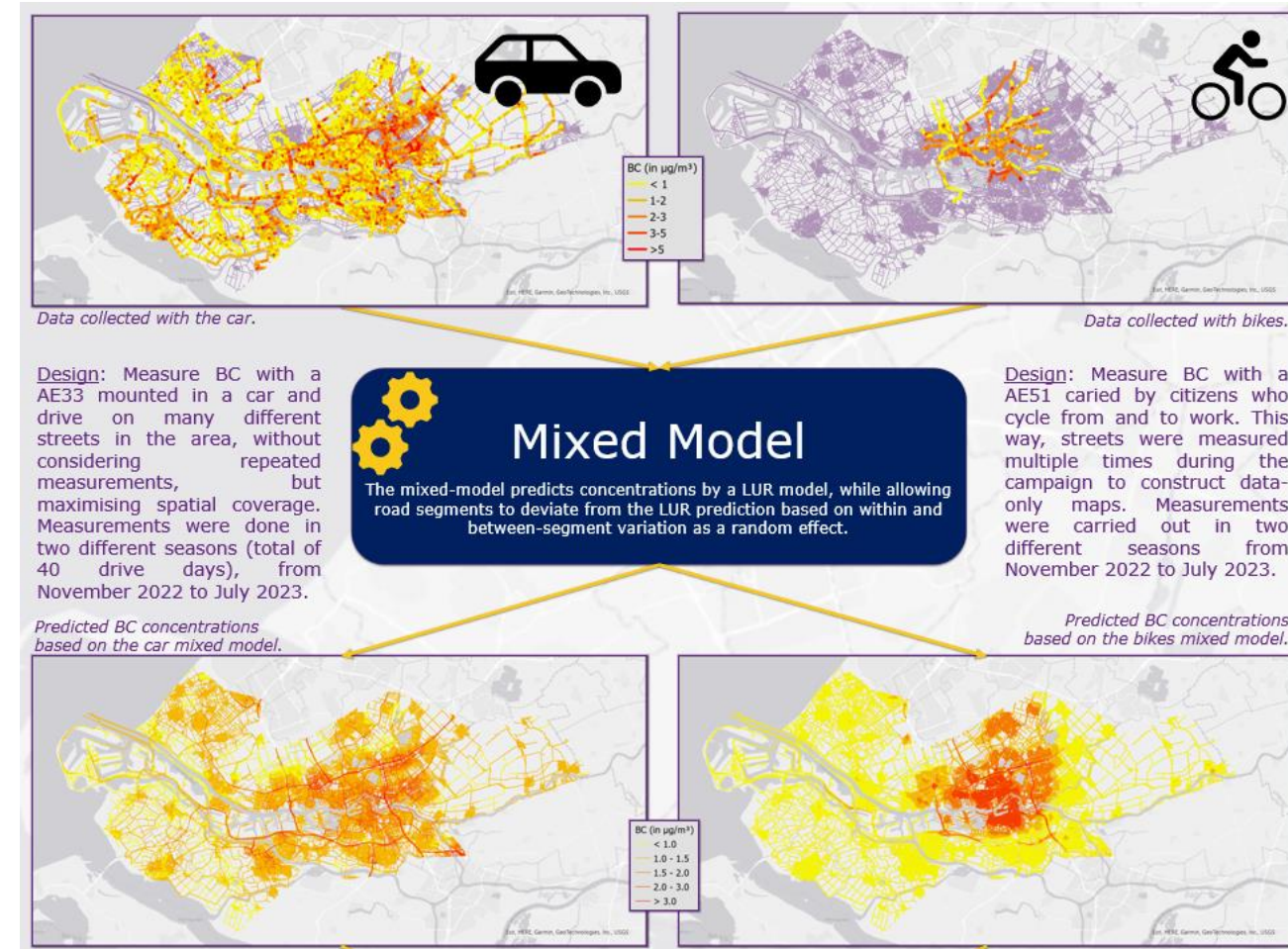
- Quality control for sensors
 - Outlier detection (related to e.g. RH)
 - Calibration by co-location to reference (representative conditions)
 - Validation instrument
 - If needed: calibration model
- Mobile monitoring
 - Measurements at different locations & times
 - Rescaling is needed to:
 - 1) Extrapolate measured averages to long-term (annual) exposure
 - 2) Rescale data collected at another period in time (~opportunistic)
 - GPS accuracy & time synchronization



$$BC_{norm,i} = BC_i - BC_{bg,i} + \overline{BC}_{bg}$$

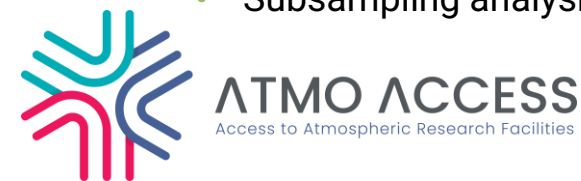
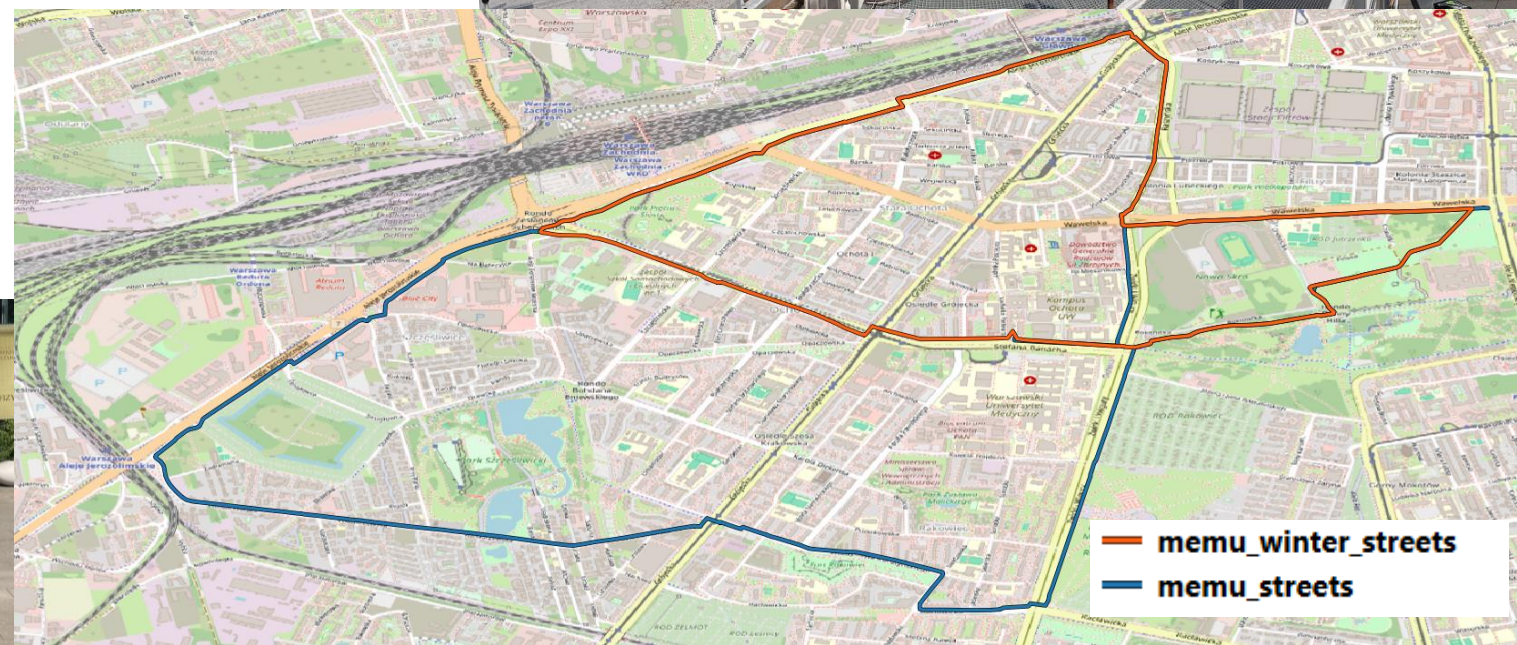
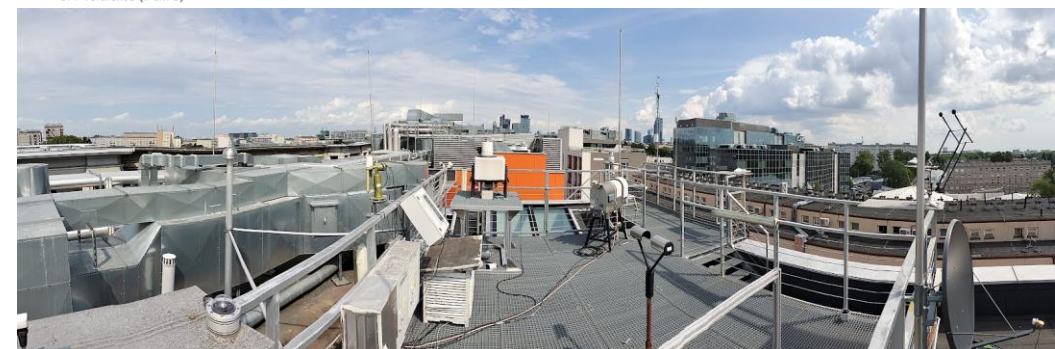
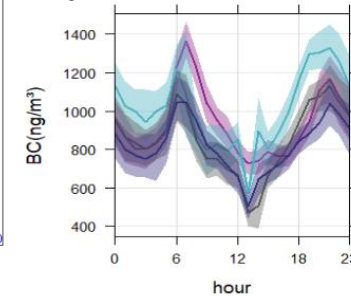
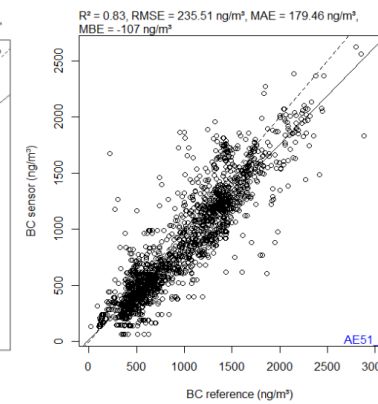
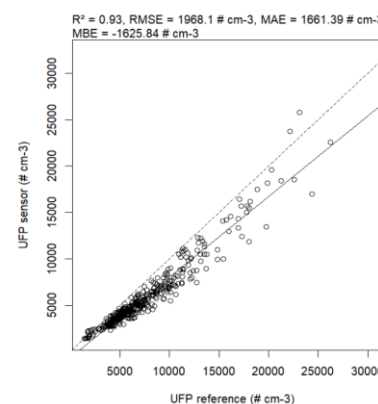
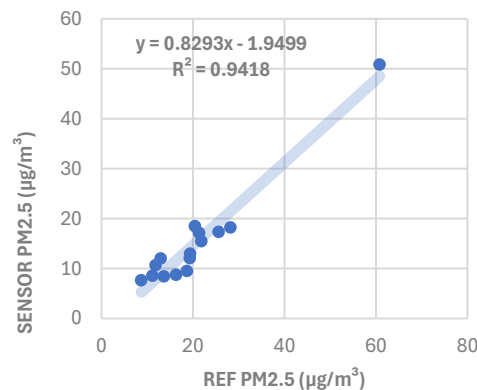
Data processing - modelling

- Data-only vs modelling strategy
- Modelling strategy
 - Mobile maps as input for LUR-based models e.g. Rotterdam
 - Measurements as validation for dispersion models:
e.g. Rotterdam data showed discrepancies in model assumptions (e.g. urban ventilation)

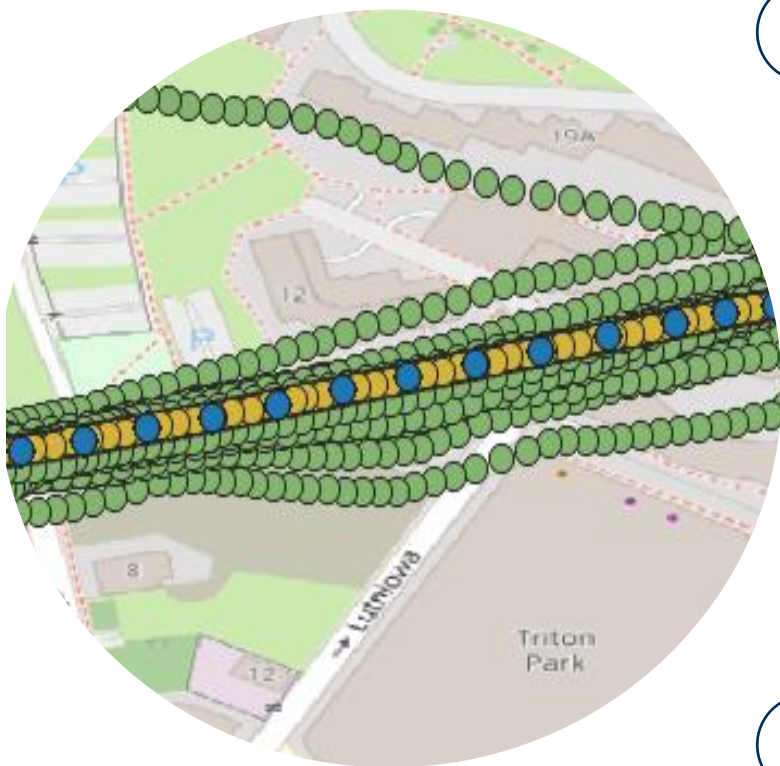


WARSAW

- Upscaling city → ST13
- Multi-pollutant: BC, UFP and PM
- Rush hours: 8-9h & 17-18h
- Co-location campaign
- Dedicated route (n=40)
 - Summer: 6/9 – 9/10
 - Winter: 22/1 – 5/3
- Pollutant maps + ratio's
- Subsampling analysis



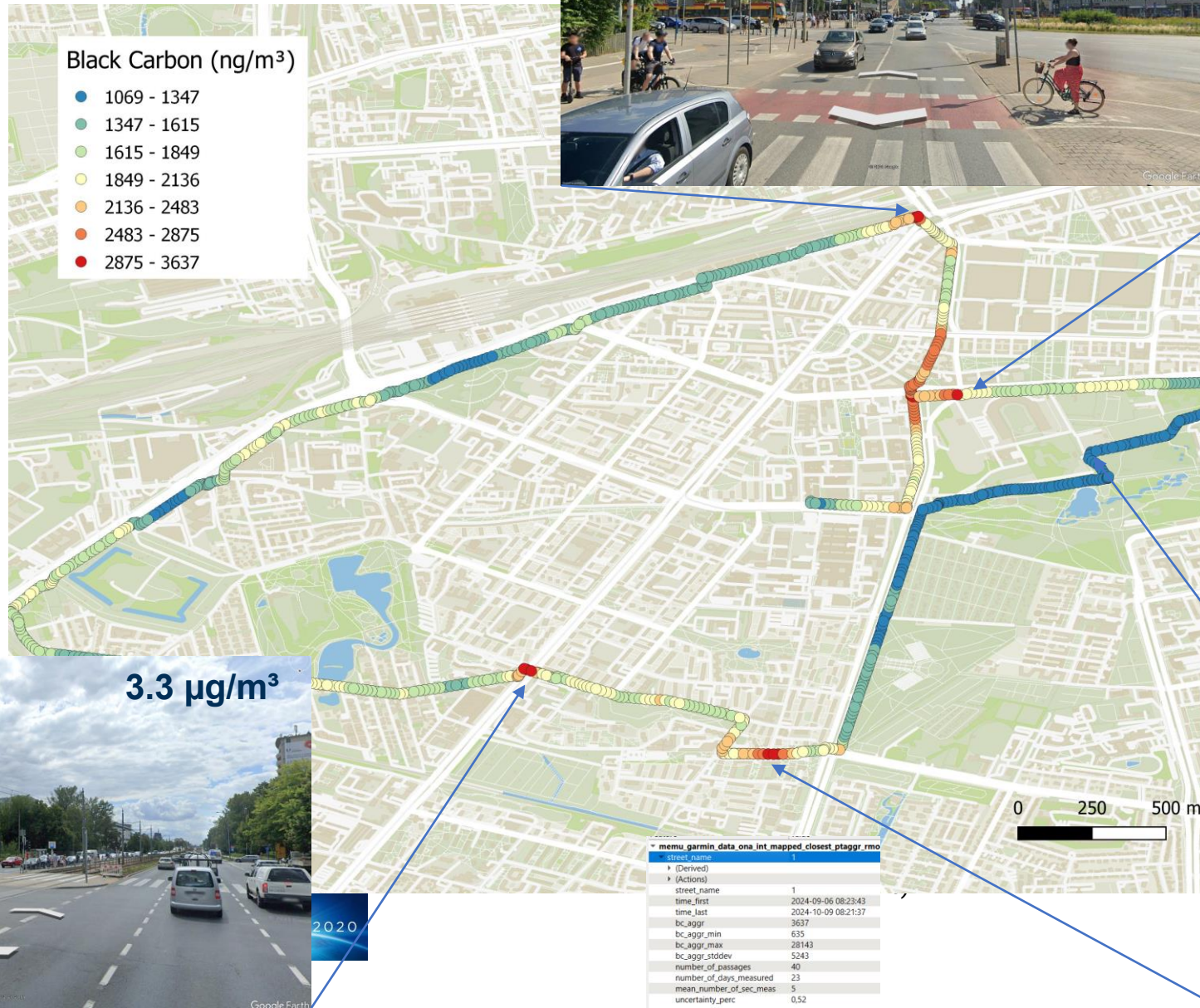
WARSAW



- SYNC GPS & MEASUREMENTS (1 SEC)
- NOISE CORRECTION BC (ONA)
- MATCH MEASUREMENTS TO SEGMENTS
- BACKGROUND NORMALISATION
- AGGREGATE MEASUREMENTS IN BUFFERS
- BUFFER AVERAGE FOR EVERY PASSAGE
- AVERAGE MULTIPLE PASSAGES

BC HOT/COLDSPOTS

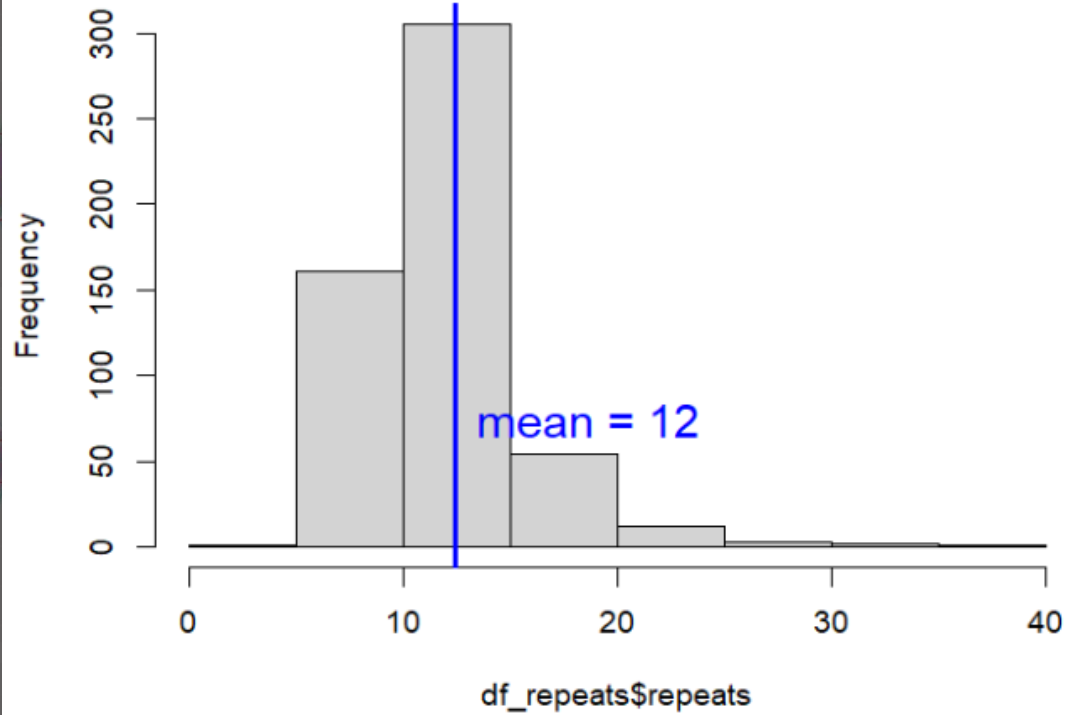
AVG n=40



WINTER (n=539)

SUMMER (n=894)

Histogram of df_repeats\$repeats



Histogram of df_repeats\$repeats

